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TECHNICAL JOB
SPECIFICATION

610/2

REVISION 0

DATE 05/04/2011

HIGH PRESSURE (HP) TRANSMISSION SYSTEMS

INSTRUMENTATION SYMBOLS AND IDENTIFICATION



Job Spec. No 610/2 Revision 0

Date 05-04-2011

Page 2/27

QUALITY ASSURANCE PAGE

CHANGES LOG

REVISIONS LOG

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0	05-04-2011	FIRST ISSUE	PQ DPT.		V.G.
Rev. No	Rev. Date	REASON FOR CHANGE	Made By		Approved By

ODESFA

HELLENIC GAS TRANSMISSION SYSTEM OPERATOR

Job Spec. No 610/2 Revision 0

Date 05-04-2011

Page 3/27

CONTENTS

REFERENCED DOCUMENTS

- 1.0 GENERAL
- 2.0 FUNCTIONAL IDENTIFICATION
- 3.0 LOOP IDENTIFICATION
- 4.0 SYMBOLS
- 5.0 ATTACHED DOCUMENTS



Job Spec. No 610/2

Revision
Date

05-04-2011

Page

4/27

REFERENCED DOCUMENTS

1. ISA S5.1 (1984)
[Instrumentation Symbols and Identification]

2 ISA S5.3(1983)
[Graphic Symbols for Distributed Control / Shared Display Instrumentation Logic and Computer Systems]



Job Spec. No 610/2 Revision 0

Date 05-04-2011

Page 5/27

1.0 GENERAL

Instruments shall be identified by a system of letters and numbers generally in accordance with the Instrument Society of America (ISA) Standards S5.1, and S5.3 last edition, extracts from which follow. Minor modifications have been made, in this specification.

Each instrument will be identified first by a system of letters used to classify it functionally. (See **Tables 1 and 2** for the system of letters). To establish a loop identity for the instrument, a number will be appended to the letters. This number will, in general, be common to other instruments of the loop of which this instrument is a part. A suffix is sometimes added to complete the loop identification.

Where **ISA Standards S5.1 and S5.3** offer alternate methods of presentation, Owner practice is to use the method requiring the fewest symbols.

Symbols will not be shown for the following:

- a) Valve positioners.
- b) Field mounted I/P transducers, when no solenoid valve or other device is in line between I/P and valve.
- c) Balloons identifying flow and temperature primary elements.
- d) Multiplexing, when used for panel mounted temperature indication only.
- e) Local process variable indicators on transmitter outputs, unless it is intended to designate a special location for the indicator, as shown by a note next to the tagging balloon.

2.0 FUNCTIONAL IDENTIFICATION

The functional identification of an instrument will consist of letters from **Table 1**, and will include on first-letter, covering the measured or initiating variable, and one or more succeeding letters covering the functions of the individual instrument. Exceptions to this rule are the use of the single letter L to denote a pilot light that is not part of an instrument loop and certain computer functions which will use modifying letters only.

The succeeding-letters of the functional identification designate one or more readout or passive functions, or output functions, or both. A modifying-letter may be used, if required, in addition to one or more other succeeding-letters. Modifying letters may modify either a first-letter or other succeeding-letters, as applicable. All letters of the functional identification shall be upper case. For examples of combinations of functional identification letters, see Table 2.

The functional designation associated with relays and computers may be used, as shown in **Table 3**, individually or in combination. The use of a box enclosing a symbol is required. The box is intended to avoid confusion by setting off the symbol from other markings on a diagram.





Job Spec. No 610/2 Revision 0

05-04-2011 Date Page 6/27

TABLE 1 **IDENTIFICATION LETTERS**

	FIRST - LE	ETTER (2.3.2)	SUCCEEDING - LETTERS					
	MEASURED OR INIATING VARIABLE	MODIFIER	READOUT OR PASSIVE FUNCTION	OUTPUT FUNCTION	MODIFIER			
Α	Analysis (2.3.4)		Alarm					
В	Bumer, Combustion	->	User's Choice (2.3.1)	User's Choice (2.3.1)	User's Choice (2.3.1)			
С	Heating Value			Control				
D	Density	Differential (2.3.2)						
Ε	Voltage		Sensor (Primary Element)					
F	Flow Rate	Ratio (Fraction) (2.3.2)						
G	User's Choice (2.3.1)		Glass, Viewing Device					
Н	Hand				High			
1	Current (Electrical)		Indicate					
J	Power	Scan						
K	Time, Time Schedule	Time Rate of Change (2.3.2., 2.3.7)		Control Station (2.3.7)				
L	Level		Lignt (2.3.5)		Low			
М	Energy	Momentary (2.3.2)			Middle Intermediate			
N	User's Choice (2.3.1)		User's Choice (2.3.1)	User's Choice (2.3.1)	User's Choice (2.3.1			
0	User's Choice (2 3.1)		Orifice, Restriction					
Р	Pressure. Vacuum		Point (Test)Connection					
Q	Quantily	Integrate, Totalize (2.3.2)						
R	Radiation	}	Record					
S	Speed, Frequency	Safety		Switch				
T	Temperature			Transmit				
U	Multivariable (2.3.8)		Multifunction (2.3.9)	Multifunction (2.3.9)	Multifunction (2.3.9)			
V	Vibration, Mechanical Analysis			Valve, Damper, Louver				
W	Weight, Force		Well	****				
Х	Unclassified (2.3.3)	X Axis	Unclassified (2.3.3)	Unclassified (2.3.3)	Unclassified (2.3.3)			
Υ	Event, State or Presence	Y Axis		Relay, Compute Convert				
Z	Position, Dimension	Z Axis		Driver, Actuator, Unclassified Final Control Element				

610/2



Job Spec. No 610/2 Revision

Date

05-04-2011

Page

7/27

2.1 Notes For Table 1 - Meaning of Identification Letters

A user's choice letter is intended to cover unlisted meanings that will be used repetitively in a particular project. If used, the letter may have one meaning as a first-letter and another meaning as a succeeding-letter. For example, the letter N may be defined as "modulus of elasticity" as a first-letter and "oscilloscope" as a succeeding-letter.

Any first-letter, if used in combination with modifying letters D (differential or deviation), F (ratio), M (momentary), K (time rate of change), Q (integrate or totalize), or any combination of these is intended to represent a new and separate measured variable, and the combination is treated as a first-letter entity. Thus, instruments TDI and TI indicate two different variables, namely, differential- temperature and temperature. Modifying letters are used when applicable.

The unclassified letter X is intended to cover unlisted meanings that will be used only once or to a limited extent. If used, the letter may have any number of meanings as a first-letter and any number of meanings as a succeeding - letter. Except for its use with distinctive symbols, it is expected that the meanings will be defined outside a tagging balloon on a flow diagram. For example, XR-2 may be a stress recorder, XR-3 may be a vibration recorder, and XX-4 may be a stress oscilloscope.

First-letter A for analysis covers all analyses that are not listed in TABLE 1 and are not covered by a user's choice letter. It is expected that the type of analysis in each instance will be defined outside a tagging balloon on a flow diagram.

A pilot light that is part of an instrument loop should be designated by a first-letter followed by the succeeding- letter L. For example, a pilot light that indicates an expired time period should be tagged KQL. If it is desired to tag a pilot light that is not part of an instrument loop, the light is designated in the same way. For example, a running light for an electric motor may be tagged EL, assuming voltage to be appropriate measured variable, or YL, assuming the operating status is being monitored. The unclassified variable X should be used only for applications which are limited in extent. The designation XL should not be used for motor running lights, as these are commonly numerous. It is permissible to use the user's choice letters M. N or O for a motor running light when the meaning is previously defined. If M is used, it must be clear that the letter does not stand for the word "motor", but for a monitored state.

If a given loop has more than one instrument with the same functional identification, then a suffix shall be appended to the loop number, e.g. FV- 2A, FV-2B, etc., or TE-25-1, TE-25-2, etc.

However, if digital systems are involved, the use of suffixes may not be compatible and unique consecutive numbers shall be used. In such cases, using flow as an example, the main instrument should take the number of the Primary Case, e.g. with High and Low Flow arrangement, the transmitters shall be numbered, say FT-2 and FT-3, while the main instrument would be numbered FRC-2.

Modifying-letter K, in combination with a first-letter such as L, T, or W, signifies a time rate of change of the measured or initiating variable. The variable WKIC, for instance, may represent a rate-of- weight-loss controller.



Job Spec. No 610/2 Revision 0

Date 05-04-2011

Page 8/27

Succeeding-letter K is a user's option for designating a control station, while the succeeding-letter C is used for describing automatic or manual controllers.

Use of first-letter U for "multivariable" in lieu of a combination of first-letters is optional. It is recommended that nonspecific variable designators such as U be used sparingly.

Use of a succeeding-letter U for "multifunction" instead of a combination of other functional letters is optional.

This non-specific function designator should be used spaningly.





Job Spec. No 610/2

Revision

u 05-04-2011

Date Page

9/27

TABLE 2 TYPICAL LETTER COMBINATIONS

	MEASURED VARIABLE RUWENT CTION	ANALYSIS	DENSITY	FLOW	LEVEL	PRESSURE	PRESSURE DIFFERENTIAL	SPEED	TEMPERATURE	TEMPERATURE DIFFERENCE
RECORDING CONTROL V	R CONTROLLER CONTROLLER ALVE ALVE-SELF ACTING W H	AE AI AT ARC AIC ARC AV ASL AAH AY	OE OI OI OR DC DIC DRC DX DSH DSH DAL OAH OY	FE ST FE C C C C C C C C C C C C C C C C C C	TETERSES SECTIFIED	PE PI PR PC PIC PRC PV PSL PAL PAH PY	POE PDI POT POR POC POC POC POSL PDSL PDSL PDAL PDAL PDAL PDY	SE SI ST SR SC SIC SRC SY SSL SAH SAH SY	TE TI TI TR TC TRC TV TCV TSL TAH TY	
SES CELECOPES SESSES SES SES SES SES SES SES SES S	BURNER FLAME DETECTOR FLAME DETECTION SWITCH ELECTRICAL CONDUCTIVITY PRO VOLTAGE INDICATOR INDICATION LIGHT FLOW SIGH GLASS (FLAPPER, FLOW RESTRICTION ORIFICE INDICATION OF INTEGRATED FL INDICATION WITHOUT COMMANUAL LOADING STATION WITHAND SWITCH HAND SWITCH HAND SWITCH (LOADING STATION WITHAND SWITCH (LOW OR CIPOSITION SWITCH (LOW OR CIPOSITION SWITCH (HIGH OR CIPOSITION SWITCH (HIGH OR CIPOSITION SWITCH (HIGH OR CIPOSITION FROM OR CLOSED INTEGRATION HIGH OR OPEN POTREND RECORDER MULTIPLEXING UNIT, WHEN US	ETC.) OW AND OW AND ARIZING) H OUTPH LIGHT H OUTPH LOSED) PEN) POSITION	IT CAUG	E E AND P	ROCESS	INDICAT				



Job Spec. No 610/2

No 610/2 0

Revision Date

05-04-2011

Page

10/27

TABLE 3 DESIGNATION FOR RELAYS AND COMPUTER FUNCTIONS

NO	FUNCTION	SYMBOL	DEFINITION
1	SUMMING	Σ	THE OUTPUT EQUALS THE ALGEBRAIC SUM OF THE INPUTS. (THE INPUTS MAY BE LABELED WITH POSITIVE OR NEGATIVE SIGNS).
2	AVERAGING	E.F	THE OUTPUT EQUALS THE ALGEBRAIC SUM OF THE INPUTS DIVIDED BY THE NUMBER OF INPUTS.
3	DIFFERENCE	Δ	THE OUTPUT EQUALS THE ALGEBRAIC DIFFERENCE OF THE TWO INPUTS.
4	PROPORTIONAL.	1:1 2:1	THE OUTPUT IS DIRECTLY PROPORTIONAL TO THE INPUT. IN THE CASE OF A VOLUME BOOSTER, "K" MAY BE REPLACED BY 1:1. FOR INTEGER GAINS, 2:1, 3:1,ETC., MAY BE SUBSTITUTED FOR K.
5	INTEGRAL	<u>.</u>	THE OUTPUT VARIES IN ACCORDANCE WITH BOTH MAGNITUDE AND DURATION OF THE INPUT. THE OUTPUT IS PROPORTIONAL TO THE TIME INTEGRAL OF THE INPUT.
6	DERIVATIVE	441	THE OUTPUT IS PROPORTIONAL TO THE RATE OF CHANGE (DERIVATIVE) OF THE INPUT,
7	MULTIPLYING	X	THE OUTPUT EQUALS THE PRODUCT OF THE TWO INPUTS.
8	DIMDING	÷	THE OUTPUT EQUALS THE QUOTIENT OF THE TWO INPUTS.
9	ROOT EXTRACTION	<u>~</u>	THE OUTPUT EQUALS THE ROOT (LE., CUBE ROOT, FOURTH ROOT, 3/2 ROOT, ETC.) OF THE INPUT. IF n IS OMITTED, A SQUARE ROOT IS ASSUMED.
10	EXPONENTIAL	x ⁿ	THE OUTPUT EQUALS THE INPUT RAISED TO A POWER (I.E., SECOND, THIRD, FOURTH, ETC.).
11	NONLINEAR OR UNSPECIFIED FUNCTION	f(x)	THE DUTPUT EQUALS SOME NONLINEAR OR UNSPECIFIED FUNCTION OF THE INPUT.
12	TIME FUNCTION	1(4)	THE OUTPUT EQUALS THE INPUT TIMES SOME FUNCTION OF TIME OR EQUALS SOME FUNCTION OF TIME ALONE.

Job Spec. No 610/2 Revision

Date

05-04-2011

Page 11/27

TABLE 3 (Contd.)

СИ	FUNCTION	SYMBOL	DEFINITION
13	HIGH SELECTING	2	THE GUTPUT IS EQUAL TO THE GREATER OF THE INPUTS.
;4	LOW SELECTING	[<]	THE OUTPUT IS EQUAL TO THE LESSER OF THE INPUTS.
15	HIGH EIMITING	>	THE OUTPUT EQUALS THE INPUT OR THE HIGH LIMIT VA. JE WHICHEVER IS LOWER.
16	LOW LEWITING		THE OUTPUT EQUALS THE INPUT OR THE LOW LIMIT VALUE WHICHEVER IS HIGHER.
17	REVERSE PROPORTIONAL	<u>-</u> K	THE CUTPUT IS REVERSELY PROPORTIONAL TO THE INPUT.
18	VELOCITY LIMITER	*	THE OUTPUT EQUALS THE IMPUT AS LONG AS THE RATE OF CHANGE OF THE INPUT DOES NOT EXCEED A LIMIT VALUE. THE OUTPUT WILL CHANGE AT THE RATE ESTABLISHED BY THIS LIMIT UNTIL THE OUTPUT AGAIN EQUALS THE INPUT.
19	8:45	+	THE OUTPUT EQUALS THE INPUT PLUS (OR MINUS) SOME ARBITRARY VALUE (BIAS).
20	CONVERT	7.	THE FORM OF THE OUTPUT SIGNAL IS DIFFERENT FROM THAT OF THE INPUT. E-VOLTAGE A-ANALOG O-ELECTROMAGNETIC, SONIC I -CURRENT B-BINARY R-RESISTANCE (ELECT.) P-PNEUMATIC H-HYDRAULIC D-DIGITAL
21	SIGNAL MONITOR	FAHL	THE OUTPUT HAS DISCRETE STATES WHICH ARE DEPENDENT ON THE VALUE OF THE IMPUT, WHEN THE IMPUT EXCEEDS (OR BECOMES LESS THAN) AN ARBITRARY LIMIT VALUE THE OUTPUT CHANGES STATE.

ODESFA

HELLENIC GAS TRANSMISSION SYSTEM OPERATOR

Job Spec. No 610/2

Revision

05-04-2011

Date Page

12/27

3.0 LOOP IDENTIFICATION

The loop identification of an instrument will generally use a number assigned to the loop of which the instrument is a part. Each instrument loop shall have a unique number. An instrument common to two or more loops may have a separate loop number, if desired.

A consecutive numbering of instruments shall be used for each process variable of a contract. The loop numbering sequence for each process variable will begin with the number 001 and run consecutively until all loops in a given contract/process unit are identified.

It is Owner practice to assign a new contract number to each section of a multi-section job. Therefore, to discriminate between such sections, the functional identification letters will be followed by two digits of the process unit number, as follows:

FIC

29

001

Functional

Unit

Progressive number

Identification

Number

4.0 SYMBOLS

It is not the intention of this standard to list all symbols or combinations. **ISA Standards S5.1 and S5.3** list many more.

Control valve positioners and control valve electric-to-air converters will not be shown. Therefore, with an electrical system, the controller output (electrical) signal will be schematically shown connected to the valve diaphragm, while the actual installation will have a converter.

Various expedients may be used on individual contracts. For example, the letter "V" just outside the circle can indicate an item supplied by a Package Vendor.

The actuator action in the event of actuating medium failure shall be shown on control valves (see typical control valve symbols).

Software alarms shall follow **ISA Standards sections 5.1 and 5.3.** Letter designators shall be placed on the input or output signal lines of controls or other specific system function.



Job Spec. No 610/2 0

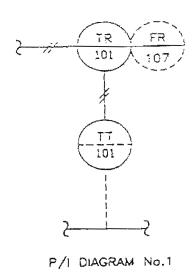
Revision

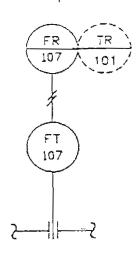
05-04-2011

Date Page

13/27

When dual pen instruments are shown on different flow diagrams, a note can show "To second pen on TR-101" or the tangential circle can be shown in phantom as follows:





P/I DIAGRAM No.2

Computer functions will be shown as an hexagon. Use modifying letters only since the measured variable "UJ" is implied by the hexagon.

The symbols used to depict instrumentation on flow diagrams and other drawings are shown on Appendix 1.

5.0 **ATTACHED DOCUMENTS**

1. Appendix 1

[Instrument Symbols]

Job Spec. No 610/2

Revision Date

0 05-04-2011

Page

14/27

APPENDIX 1

<u>INS</u>	STRUMENT LINE SYMBOLS				
	CONNECTION TO PROCESS	(Note 1)			
	UNDEFINED SIGNAL				
	PNEUMATIC SIGNAL	(Note 2)			
	ELECTRIC SIGNAL				
	HYDRAULIC SIGNAL				
××	CAPILLARY TUBING (FILLED SYSTEM)				
	ELECTROMAGNETIC (NUCLEAR) OR SONIC SIGNAL (GUIDED)	(Note 3)			
~ ~	ELECTROMAĞNETIC OR SONIC SIGNAL (NOT GUIDEO)	(Note 3)			
o o	INTERNAL SYSTEM LINK (SOFTWARE OR DATA LINK)				
	MECHANICAL LINK				
OPTIONA	L BINARY (ON-OFF) SYMBOLS				
- * *-	PNEUMATIC BINARY SIGNAL				
\\	ELECTRIC BINARY SIGNAL				
Notes :					
1. All lines to be fine in relation					
	opplies to a signal using any gos as the signal medium. ed. the gas may be identified by a note on the signal sy	mbol or			
3. Electromagnetic phenomena include heat, radio waves, nuclear radiation, and light.					



Job Spec. No 610/2 Revision 0

Date

05-04-2011

Page

15/27

GENERAL INSTRUMENT OR FUNCTION SYMBOLS

	PRIMARY LOCATION *** NORMALLY ACCESSIBLE TO OPERATOR	FIELD NOUNTED	AUXILIARY LOCATION VAA NORMALLY ACCESSIBLE TO OPERATOR
DISCRETE INSTRUMENTS	1 1P1aw	2	3
SHARED DISPLAY, SHARED CONTROL	4	5	6
COMPUTER FUNCTION	7	8	9
PROCRAMMABLE LOGIC CONTROL	10		12

- Symbol size may vary according to the user's needs and the type of document. A suggested square and circle size for large diagrams is shown above. Consistency is recommended.
- Abbreviations of the user's choice such as IP1 (Instrument Panel #1), IC2 (Instrument Console #2), CC3 (Camputer Console #3) etc., may be used when it is necessary to specify instrument or function location.

***	Normally	inoccessible	or t	behind-	the-pané	devices	٥r	functions	may	Þе	depicted	bу	បនាំពិច្ច	the	same	symbol
	but ⊬ îth	dashed hori	zonto	d bar∍.	ì.e. ($\overline{\left(-\right)}$	K	7	\rightarrow							

ODESFA

HELLENIC GAS TRANSMISSION SYSTEM OPERATOR

Job Spec. No 610/2 Revision 0

Date Page

05-04-2011 16/27

GENERAL INSTRUMENT OR FUNCTION SYMBOLS (Contd.)

13	14	15			
	7ξ 31001.23				
REPORT ON PRINTER	INSTRUMENT WITH LONG TAG NUMBER	INSTRUMENTS SHARING COMMON HOUSING			
16	17 C 12	18 \$\begin{align*} \(\begin{align*} \perp \\ \perp \end{align*}			
PILOT LIGHT	PANEL MOUNTED PATCHBOARD POINT 12	PURGE OR FLUSHING DEVICE			
19	20	21			
⟨R⟩	5≥	⟨i⟩			
RESET FOR LATCH-TYPE ACTUATOR	DIAPHRAGM SEAL	UNDEFIND INTERLOCK LOGIC			



Job Spec. No 610/2

Revision

0

Date Page 05-04-2011 17/27

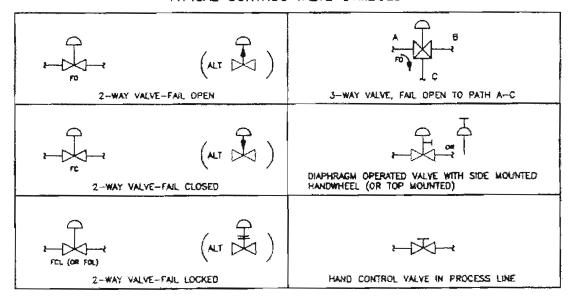
CONTROL VALVE BODY SYMBOLS, DAMPER SYMBOLS

├	-	2—[*]?	├ ───
GENERAL SYMBOL	ANGLE	BUTTERFLY	ROTARY VALVE
		;— [∞]—	甲
THREE-WAY	FOUR-WAY	GLOBE	DAMPER OR LOUVER

ACTUATOR SYMBOLS

7	F	M	S
DIAPHRAGM TYPE ACTUATOR	PISTON TYPE ACTUATOR	MOTOR ACTUATOR	SOLENOID ACTUATOR

TYPICAL CONTROL VALVE SYMBOLS





Job Spec. No 610/2

Revision

0

Date Page 05-04-2011 18/27

PRIMARY ELEMENT SYMBOLS

} —∤	; —∰—-,	⊢ ∑	H
ORIFICE PRIMARY ELEMENT	PITOT-TUBE OR ANNUBAR	venturi tube or Flow Nozzle	ROTAMETER TYPE PLOW METER
⊢	}— □	<u> </u>	<u>⊢</u> ®→
LINE TYPE FLOW METER	vortex flow meter		POSITIVE DISPLACEMENT-TYPE FLOW TOTALIZING INDICATOR





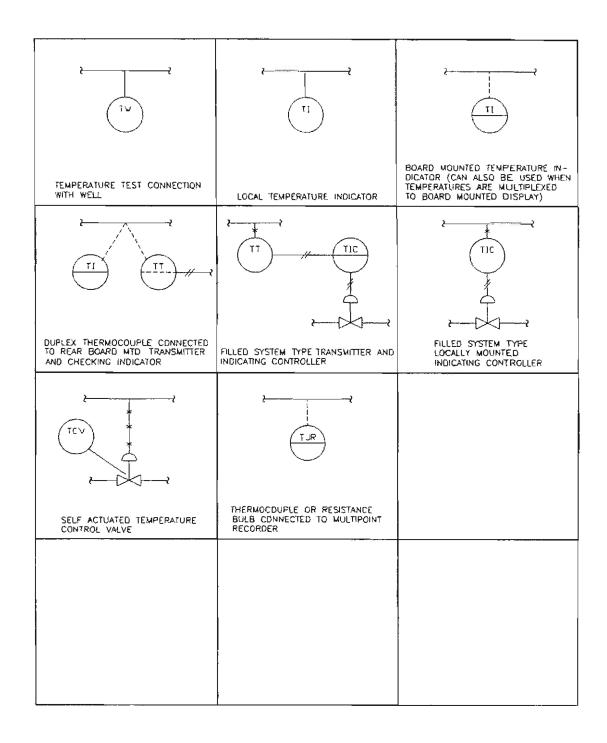
Job Spec. No 610/2 Revision 0

Date

05-04-2011

Page

19/27

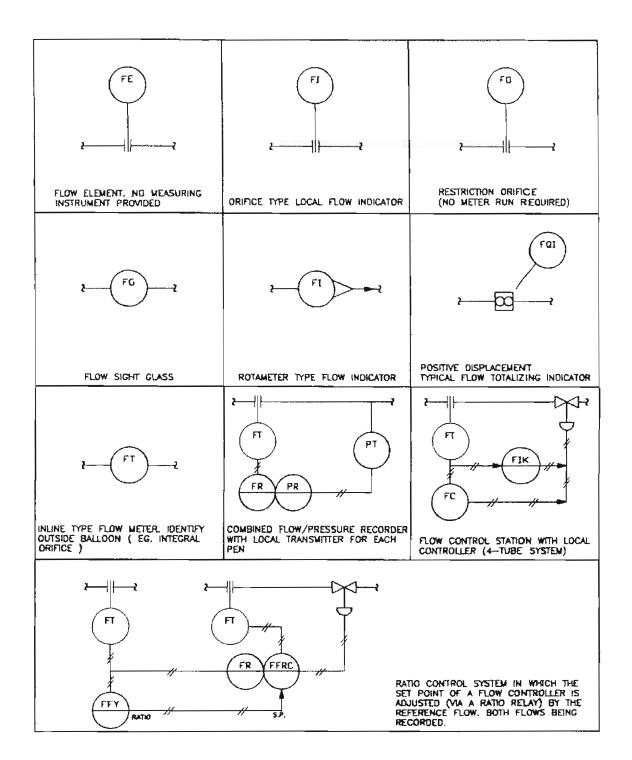




Job Spec. No 610/2 Revision 0

Date 05-04-2011

Page 20/27





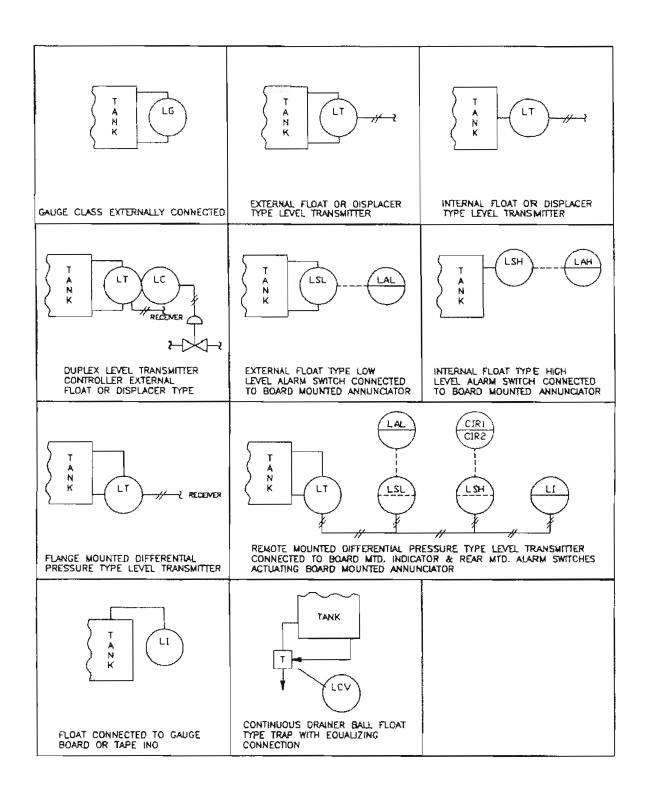


Job Spec. No 610/2

Revision

0

Date Page 05-04-2011 21/27





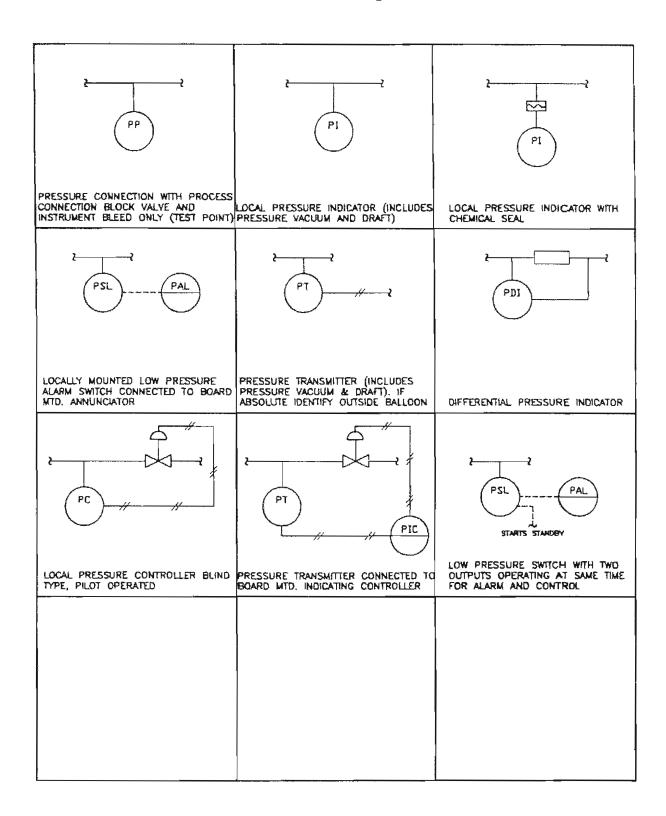
Job Spec. No 610/2 Revision 0

Date

05-04-2011

22/27

Page





Job Spec. No 610/2 Revision 0

Date 05-04-2011 Page 23/27

HAND CONTROL VALVE IN PROCESS LINE	HS ALT: 2-11-12 AL	HAND ACTUATED ELECTRIC SWITCH HAND ACTUATED ELECTRIC SWITCH WITH PILOT LIGHT
H1C / H1	ZSL ZSH ZLL ZLH ZLH	ZT
MANUAL LOADING STATION WITH OUTPUT GAUGE	POSITION SWITCHES CONNECTED TO PILOT LIGHTS INDICATING LOW (OR CLOSED) AND HIGH (OR OPEN) POSITION	POSITION TRANSMITTER
2—————————————————————————————————————	T A XG XG N K	XC V
ANALYSIS TEST SAMPLE POINT	SIGHT GLASS FOR INTERNAL VIEWING	ALL TRAPS OTHER THAN BALL FLOAT TYPE CONTINUOUS DRAINERS



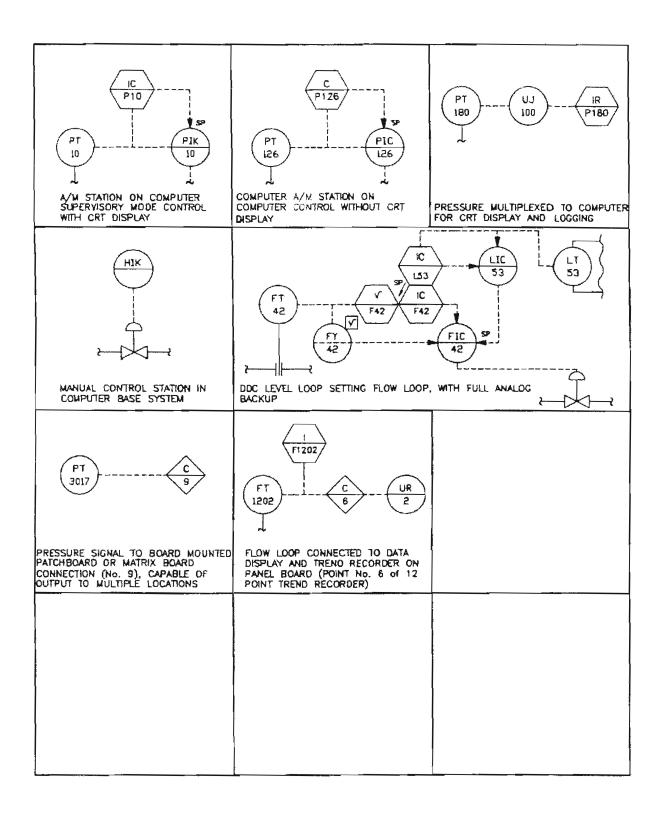
Job Spec. No 610/2

Revision

0

Date Page 05-04-2011

24/27



ODESFA

HELLENIC GAS TRANSMISSION SYSTEM OPERATOR

Job Spec. No 610/2 Revision 0

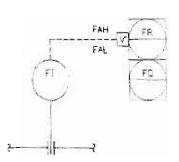
Revision Date

05-04-2011

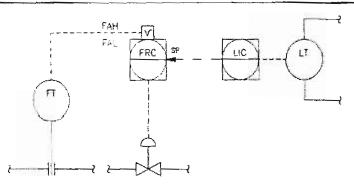
Page

25/27



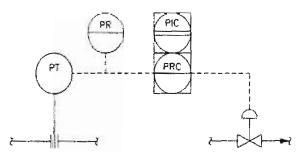


Shared Display
Shared Control
No Backup.
Cascade Cantrol Loop,
Showing V Signal
Conditioning Function,
Alarms on Measured
Variable Trend Recording Available
(Not all System Signals
have Trending Available)

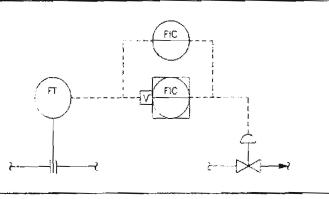


Shared control
Analogue back-up station
interfaced with the system.
Hardwired continuous analogue
recorder.
Trend recording available
(Not all System Signols
have Trending Available)

Shared display



Shared display Shared control. V signal canditioning system function, analogue control station independent from the system.

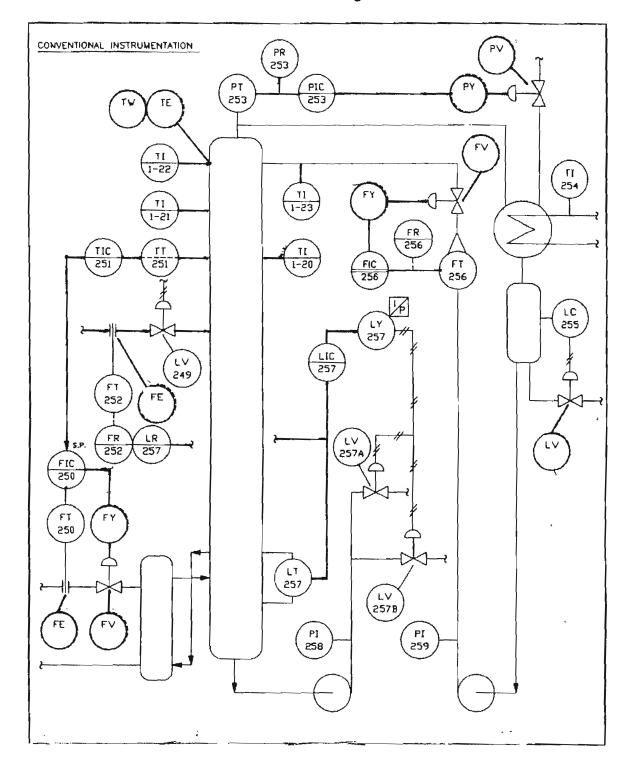




Job Spec. No 610/2

Revision 0

Date 05-04-2011 Page 26/27





Job Spec. No 610/2

Revision Date

05-04-2011

Page

27/27

